COMP 605: Introduction to Parallel Computing Lecture : Compute Unified Device Architecture (CUDA) Overview

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> Posted: 04/20/17 Last Update: 04/20/17

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Compute Unified Device Architecture (CUDA) Overview

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Introduction to Compute Unified Device Architecture (CUDA, K&W Ch3; S&K, Ch3)

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Outline:

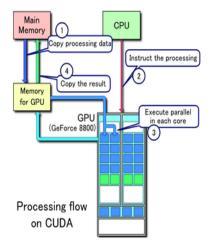
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- Memory Management



CUDA (Compute Unified Device Architecture)

Example of CUDA processing flow:

- CPU initializes, allocates, copies data from main memory to GPU memory
- OPU sends instructions to GPU
- GPU executes parallel code in each core
- GPU Copies the result from GPU mem to main mem



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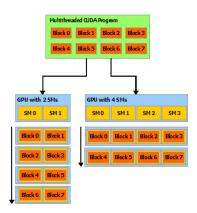
CUDA API (1)

• CUDA C is a variant of C with extensions to define:

- where a function executes (host CPU or the GPU)
- where a variable is located in the CPU or GPU address space
- execution parallelism of kernel function distributed in terms of grids and blocks
- defines variables for grid, block dimensions, indices for blocks and threads
- Requires the *nvcc* 64-bit compiler and the CUDA driver outputs PTX (Parallel Thread eXecution, NVIDIA pseudo-assembly language), CUDA, standard C binaries
- CUDA run-time JIT compiler (optional); compiles PTX code into native operations
- math libraries, cuFFT, cuBLAS and cuDPP (optional)

CUDA Programming Model

- Mainstream processor chips are parallel systems: multicore CPUs and many core GPUs
- CUDA/GPU provides three key abstractions:
 - hierarchy of thread groups
 - shared memory
 - barrier synchronization
- fine-grained data & thread parallelism, nested within coarse-grained data & task parallelism
- partitions problem into coarse sub-probs solved with parallel independent blocks of threads
- sub-problems divided into finer pieces solved in parallel by all threads in block
- GPU has array of Streaming Multiprocs (SMs)
- Multithreaded program partitioned into blocks of threads that execute independently from each other
- Scales: GPU (more MPs) executes in less time than GPU (fewer MPs).



Source: NVIDIA cuda-c-programming-guide

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CUDA Kernel Basics

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CUDA Code Example: simple_hello.cu (K&S Ch3)

```
[mthomas@tuckoo hello]$ cat simple_hello.cu
/*
 * Copyright 1993-2010 NVIDIA
 * Corporation.
 * All rights reserved.
 */
#include <stdio.h>
__global__ void mykernel( void ) {
 }
int main( void ) {
 mykernel<<<1,1>>>();
 printf( "Hello, GPU World!\n" );
 return 0;
}
```

CUDA code highlights:

- *mykernel* <<< 1,1>>> () directs the function to be run on the device
- mykernel() is an empty function
- __global__ is a CUDA directive that tells system to run this function on the GPU device



In its simplest form it looks like:

```
kernelRoutine <<< gridDim, blockDim >>> (args)
```

Kernel runs on the device. It is executed by threads, each of which knows about:

- variables passed as arguments
- pointers to arrays in device memory (also arguments)
- global constants in device memory
- shared memory and private registers/local variables
- some special variables:
 - gridDim: size (or dimensions) of grid of blocks
 - *blockIdx* : index (or 2D/3D indices)of block
 - blockDim: size (or dimensions) of each block
 - threadIdx: index (or 2D/3D indices) of thread



Function type qualifiers specify whether a function executes on the host or on the device and whether it is callable from the host or from the device:

- ___device___
 - Executed on GPU
 - Launched on GPU
- __global__
 - Executed on device
 - Callable from host
 - Callable from the device for devices of compute capability 3.x
- __host__ (optional)
 - Executed on host
 - Callable from host only

Source:

 $\verb+http://docs.nvidia.com/cuda/cuda-c-programming-guide/\#function-type-qualifiers$

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Grids a	nd Block	(5		

- A Grid is a collection of blocks:
 - gridDim: size (dimensions) of grid of blocks
 - blockIdx : index (2D/3D indices) of block
- A *Block* is a collection of threads (columns):
 - blockDim: size (dimensions) of each block
 - threadIdx: index (or 2D/3D indices) of thread
- *Threads* execute the *kernel* code on *device*:

Block 0	Thread 0	Thread 1	Thread 2	Thread 3
Block 1	Thread O	Thread 1	Thread 2	Thread 3
Block 2	Thread O	Thread 1	Thread 2	Thread 3
Block 3	Thread 0	Thread 1	Thread 2	Thread 3





Block Parallelism

Launch N blocks with 1 thread each:

 $add <<< N, 1 >>> (dev_a, dev_b, dev_c) >>>$

Thread Parallelism

Launch 1 block with N threads:

 $add <<<1, N >>> (dev_a, dev_b, dev_c) >>>$

We will look at examples for each type of parallel mechanisms.

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Memory Allocation

- CPU: malloc, calloc, free, cudaMallocHost, cudaFreeHost
- GPU: cudaMalloc, cudaMallocPitch, cudaFree, cudaMallocArray, cudaFreeArray

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Passing Parameters to the Kernel

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simple_kernel_params.cu (part 1)

```
#include <iostream>
#include "book.h"
__global__ void add( int a, int b, int *c ) {
        *c = a + b:
    3
int main( void ) {
int c:
int *dev c:
/* allocate memory on the device for the variable */
 HANDLE ERROR(
  cudaMalloc((void**)&dev_c, sizeof(int) ) );
/* nothing to copy -- no call to cudaMemcpy */
 /* launch the kernel */
 add<<<1.1>>>( 2. 7. dev c ):
/* copy results back from device to the host */
 HANDLE ERROR(
  cudaMemcpy(&c,dev_c,sizeof(int),cudaMemcpyDeviceToHost)
):
printf("2 + 7 = %d n", c):
cudaFree( dev c ):
return 0:
3
```

- The Kernel: *add* <<<<
 1,1>>> (2,7, *dev_c*)
 runs on the device.
- __global__ is a CUDA directive that tells system to run this function on the GPU device
- Kernel passing variables that are modified on the device.
- using 1 block with 1 thread
- Result passed from the device back to the host
- Must use pointers

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simple_kernel_params.cu (part 1)

[cuda_by_example/chapter03] nvcc -o simple_add simple_add.cu [cuda_by_example/chapter03] qsub simple_add.bat 7987.tuckoo.sdsu.edu [cuda_by_example/chapter03]\$ cat simple_device_call.o7987 simple_device_call using 1 cores...

```
2 + 7 = 9
```

```
#!/bin/bash
#
#
#PBS -V
#PPS -I nodes=node9:ppn=1
#PPS -I nodes=node9:ppn=1
#PPS -J oe
#PPS -J oe
#PPS -Q batch
cd $PPS_Q_WORKDIR
echo "Running simple_add."
./simple_add
```